

# Midterm Review

①

① Complex numbers

$$z = a + ib \Leftrightarrow z = re^{i\theta} \Leftrightarrow z = r(\cos\theta + i\sin\theta)$$

$$z^{1/m} ? \quad z^m$$

$$z = \sqrt{2} e^{\frac{\pi}{3}i} = \sqrt{2} e^{(\frac{\pi}{3} + 2\pi k)i}$$

$$\begin{aligned} z'' ? \Rightarrow z'' &= 2^{1/2} e^{(\frac{\pi}{3} + 2\pi k)i \cdot 11} \\ &= 2^{1/2} e^{(11\pi/3 + 22\pi k)i} \\ &= 2^{1/2} e^{11\pi/3 i} \end{aligned}$$

$$\begin{aligned} z^{1/11} &= 2^{\frac{1}{22}} e^{(\pi/3 + 2\pi k)i/11} \\ &= 2^{1/22} e^{(\frac{\pi}{33} + \frac{2}{11}\pi k)i} \end{aligned}$$

$\Rightarrow$  11 distinct roots  $k=0, 1, 2, \dots, 10$

$$z = a + ib$$

$$a = \operatorname{Re}(z^{1/11}) = 2^{1/22} \cos\left(\frac{\pi}{33} + \frac{2}{11}\pi k\right)$$

$$b = \operatorname{Im}(z^{1/11}) = 2^{1/22} \sin\left(\frac{\pi}{33} + \frac{2}{11}\pi k\right)$$

② know how to do

matrix/vector products

matrix/matrix products

Suppose  $A \in \mathbb{R}^{3 \times 5}$ ,  $B \in \mathbb{R}^{4 \times 3}$

Is  $AB$  well defined?

$$(3 \times 5)(4 \times 3) = \times \checkmark$$

$BA$

$$(4 \times 3)(3 \times 5) = (4 \times 5)$$

(2)

③ ID echelon form / pivot variables / Free variables

④ Row equivalence / Gaussian elimination

- know all 3 elementary operations
- note row space is invariant under elementary operations (row equivalence)  
(not true for the column vectors/space)

⑤ Matrix inverse

Be able to compute  $A^{-1}$  for  $2 \times 2$ , maybe  $3 \times 3$ ?

$2 \times 2 \Rightarrow$  use formula

$3 \times 3 \Rightarrow$  use Gaussian elimination method

$$A_2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \text{det}(A) \quad A^{-1} = \frac{1}{\text{det}(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

- know when the inverse exists!

- $A$  must be a square matrix

- $A$  must be full rank

if  $A \in \mathbb{R}^{n \times n} \Rightarrow \text{rank}(A) = n$

all column/row vectors are linearly independent

- $\text{det}(A) \neq 0$

- what is  $A^{-1}$  good for? Solving

linear system  $Ax = b$

$$A^{-1}Ax = A^{-1}b$$

$$Ix = A^{-1}b \Rightarrow \underline{x} = A^{-1}b$$

3

$A^{-1}$  for  $A \in \mathbb{R}^{3 \times 3}$

$$\left[ \begin{array}{ccc|ccc} a & b & c & 1 & 0 & 0 \\ d & e & f & 0 & 1 & 0 \\ g & h & i & 0 & 0 & 1 \end{array} \right]$$

$A$

Apply Gaussian elimination on the left-hand side (similar to when we solved  $Ax=b$ ) with augmented matrix  $[A \ b]$

Keep applying operations until the left-side looks like  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

⑥ Existence and uniqueness of solutions to  $Ax=b$

Step 1 Create augmented matrix  $[A \ b]$

Step 2 Reduce to echelon form

Step 3 Look for consistency

(if inconsistent  $\Rightarrow$  no solution)

Step 4 Look for free variables

Step 5  $\geq 1$  free variables  $\Rightarrow$  infinite soltns

0 " "  $\Rightarrow$  unique soltn

- know how to find the solution set of  $A\vec{x}=\vec{b}$

Once you have reduced to echelon form, solve for unknowns as a function of free variables if there are any

inconsistent

Example

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \quad b = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

$$[Ab] = \begin{bmatrix} 1 & 2 & | & 5 \\ 0 & 0 & | & 2 \end{bmatrix} \Rightarrow \begin{aligned} x_1 + 2x_2 &= 5 \\ \underline{0} &= \underline{2} \end{aligned}$$

inconsistent  
⇒ no solution

$$A \in \mathbb{R}^{5 \times 3} \quad Ax = b \quad x \in \mathbb{R}^{3 \times 1}$$

reduced row echelon form is

$$A \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ \hline 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

### ⑦ Linear dependence / independence

vectors  $\{v_1, v_2, \dots, v_n\}$  are linearly dependent if  $\exists k_1, k_2, \dots, k_n$  not all 0 s.t.  $k_1 v_1 + k_2 v_2 + \dots + k_n v_n = 0$

Special cases

2D vectors - we can apply a graphical representation

Consider a set of two vectors



If they lie on the same line ⇒ dependent  
otherwise ⇒ independent

5

2 vectors in  $\mathbb{R}^2$  that are linearly independent span  $\mathbb{R}^2$

3 vectors in  $\mathbb{R}^2$  are always linearly dependent

In general,  $n$  vectors in  $\mathbb{R}^n$  that are linearly indep. span  $\mathbb{R}^n$

$\Rightarrow$   $n+1$  vectors are always linearly dependent

If a set contains  $\vec{0}$ , then it is linearly dependent

- know the transpose of a matrix

$$A = \begin{pmatrix} 1 & 5 \\ 0 & 4 \\ 2 & 3 \end{pmatrix} \quad A^T = \begin{bmatrix} 1 & 0 & 2 \\ 5 & 4 & 3 \end{bmatrix}$$

⑧ spans / basis / subspace

Suppose matrix  $A \in \mathbb{R}^{11 \times 9}$

Is it possible that the matrix when reduced to echelon form has a pivot point in every row? No

$$\dim(\text{colsp}(A)) = \dim(\text{rowsp}(A)) \leq 9$$

$\Rightarrow$  2 rows of zero when reduced  
maximum 9 pivot points

(6)

Max # linearly indep. rows  
 $\equiv$  " " " " columns  
 $\equiv$  rank (A)  
 $\equiv$  # of pivot points/variables in echelon form

Ex. Suppose  $\vec{a}_1, \dots, \vec{a}_n$  are in  $\mathbb{R}^m$   
 how ~~to~~ to check if  $\text{span}\{\vec{a}_1, \dots, \vec{a}_n\} = \mathbb{R}^m$

Requirements to span  $\mathbb{R}^m$   
 need  $m$  linearly independent vectors  
 How do we check

Step 1  $n \geq m$

rank(A) = rank(A<sup>T</sup>)  
 $= \dim(\text{colsp}(A))$   
 $= \dim(\text{rowsp}(A))$

Step 2 Generate a matrix with vectors  
 $A = [\vec{a}_1, \dots, \vec{a}_n]$

Step 3 row reduce to echelon form

Step 4 determine rank (A)  
 (count up the pivot points)

Step 5 If # of pivots =  $m$   
 $\Rightarrow \text{span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\} = \mathbb{R}^m$

Consider

$$C = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ -1 & -2 & -3 & -4 & -5 \end{bmatrix} \Rightarrow \text{rank}(C) = 1$$

$$\text{colsp}(C) = \text{span}\left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix}, \dots, \begin{bmatrix} 5 \\ -5 \end{bmatrix} \right\}$$

$$\text{rank}(C) \leq 2$$

7

$$\dim(\text{colsp}(C)) = 1$$

⇒ basis for  $\text{colsp}(C)$  has 1 element

$$\text{basis is } \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{colsp}(C) = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\} = \begin{bmatrix} a \\ b \end{bmatrix} : a = -b$$

Ex If  $A \in \mathbb{R}^{6 \times 8}$ , what is the smallest possible dimension of  $\text{Nul } A$  ( $\text{Ker}(A)$ )

$$\text{rank}(A) \leq 6$$

$Ax$

$$(6 \times 8)(8 \times 1)$$

"domain"

$$\dim(\mathbb{R}^8) = \text{rank}(A) + \dim(\text{Ker}(A))$$

$\downarrow \quad \downarrow$   
 $8 \quad \leq 6$

$$\Rightarrow \dim(\text{Ker}(A)) \geq 2$$

### 9) Determinants

find the value of  $k$  for which the following matrix is not invertible

$$A = \begin{bmatrix} 1 & k & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 3 \end{bmatrix}$$

$$\text{not invertible} \Rightarrow \det = 0$$

$$\det(A) = 1 \cdot \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix} - k \begin{vmatrix} 0 & 2 \\ 1 & 3 \end{vmatrix} + 1 \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} \Rightarrow 2k = 0$$
$$= 1(3-2) - k(-2) + 1(-1) = 1 + 2k - 1 = 0 \quad k = 0$$

8

Alternatively, we can ask ~~find~~  
find  $k$  s.t.  $A$  is invertible  
 $\Rightarrow \det(A) \neq 0$

Ex Let  $A = \begin{bmatrix} 2 & 1 & 1 \\ \alpha & 1 & \alpha \\ \alpha+2 & 2 & \alpha+1 \end{bmatrix}$

Find  $\alpha$  (if it exists) that makes  
 $\text{rank}(A) = 3 \Rightarrow$  ~~odd~~

There are 3  
pivot points in  
echelon form