

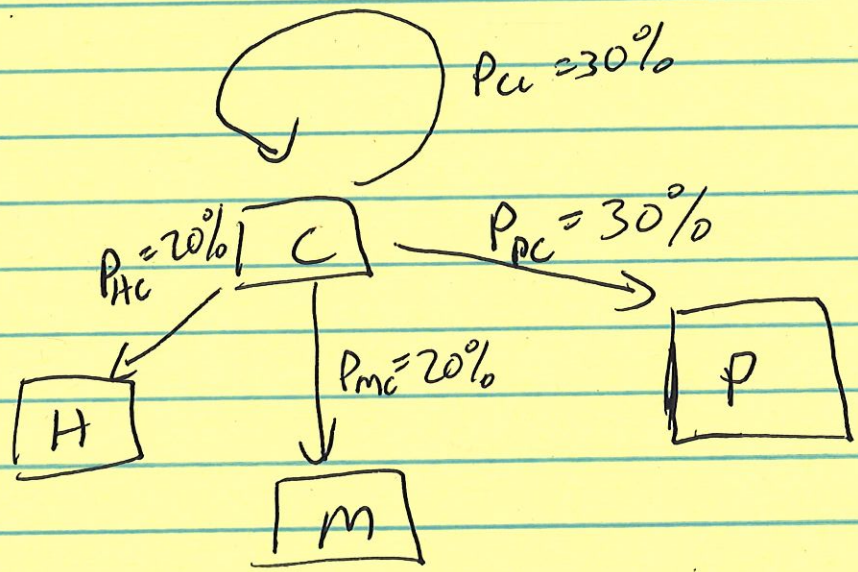


Applications of Eigenvalues

Markovian Process

Consider 4 dinner options

- C Chinese
- M Mexican
- P Pizza
- H Home



We construct a transition matrix

$$A = \begin{matrix} & \begin{matrix} H & C & M & P \end{matrix} \\ \begin{matrix} H \\ C \\ M \\ P \end{matrix} & \begin{bmatrix} .25 & .2 & .25 & .3 \\ .20 & .3 & .25 & .3 \\ .25 & .2 & .4 & .1 \\ .30 & .3 & .1 & .3 \end{bmatrix} \end{matrix}$$

$\sum_{i=1}^n a_{ij} = 1$
i, j fixed

Probability of eating at home after eating at home (points to .25)
 Probability of eating Mexican after eating Chinese (points to .2)

$[A]_{ij} = a_{ij}$ the probability of state i after I was in state j

Day 1 Suppose IC 100% probability H

$$x_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \leftarrow \begin{matrix} \text{probability} \\ \text{distribution} \end{matrix}$$

Day 2 $x_2 = Ax_1 = \begin{bmatrix} .25 \\ .20 \\ .25 \\ .30 \end{bmatrix}$

Day 3 $x_3 = Ax_2 = A^2 x_1 = \begin{bmatrix} .2550 \\ .2625 \\ .2325 \\ .25 \end{bmatrix}$

Day m $x_m = A^m x_1$

Day 30 $x_{30} = A^{30} x_1 = \begin{bmatrix} .2495 \\ .2634 \\ .2339 \\ .2532 \end{bmatrix}$

Day 50 $x_{50} = A^{50} x_1 = \begin{bmatrix} .2495 \\ .2634 \\ .2339 \\ .2532 \end{bmatrix}$ Same!

$\lim_{m \rightarrow \infty} x_m = x^*$ where $*$ denotes our equilibrium state

3

X^n captures the probability of eating at any restaurant over a long period of time

Why can we guarantee convergence?

Perron - Frobenius theorem

Let $A \in \mathbb{R}^{n \times n}$ be a positive square matrix, All entries $a_{ij} > 0$. Then the largest eigenvalue has algebraic multiplicity 1 and is a positive real number.

For a transition matrix (stochastic matrix) that eigenvalue is 1.

$$1 = |\tau_1| > |\tau_2| > |\tau_3| > \dots > |\tau_n|$$

Assume A is diagonalizable (not always true)

$$A^m = (PDP^{-1})^m = PD^mP^{-1} \\ = P \begin{bmatrix} \tau_1^m & & & \\ & \tau_2^m & & \\ & & \dots & \\ & & & \tau_n^m \end{bmatrix} P^{-1}$$

if $|\tau_i| < 1$

$$\lim_{m \rightarrow \infty} \tau_i^m = 0$$

Recall, that A is diagonalizable if and only if its eigenvectors are linearly indep.

$A \in \mathbb{R}^{n \times n} \Rightarrow n$ linearly independent eigenvectors in \mathbb{R}^n

$$\text{Span} \left\{ \vec{v}_1, \dots, \vec{v}_n \right\} = \mathbb{R}^n$$

↑
eigenvectors

Then

$$\lim_{m \rightarrow \infty} A^m x = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$
$$= c_1 \vec{v}_1$$

x^* : equilibrium state is ~~the~~ an eigenvector associated with $\lambda = 1$

Such guarantees cannot be made if there are zero entries $a_{ij} > 0$

Example

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

Let's compute eigenvalues!

5

$$sI - A = \begin{bmatrix} s & -1 & 0 \\ 0 & s & -1 \\ -1 & 0 & s \end{bmatrix}$$

$$\det(sI - A) = s \begin{vmatrix} s & -1 \\ 0 & s \end{vmatrix} + 1 \begin{vmatrix} 0 & -1 \\ -1 & s \end{vmatrix}$$

$$= s^3 - 1 = 0$$

$$s^3 = 1 = e^{i2\pi k}$$

$$= \cos(2\pi k/2) + i \sin(2\pi k)$$

⇒ 3 eigenvalues

$$\left(e^{i2\pi k} \right)^{1/3}$$

$$s = e^{i \frac{2}{3}\pi k}$$

k=1

$$\gamma_1 = e^{i2\pi/3} = \cos(2\pi/3) + i \sin(2\pi/3)$$

k=2

$$\gamma_2 = e^{i4/3\pi} = \cos(4/3\pi) + i \sin(4/3\pi)$$

k=3

$$\gamma_3 = e^{i2\pi} = 1$$

$$|\gamma_1| = |\gamma_2| = |\gamma_3| = 1$$

periodic Markov Chain

$$A^{100} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$A^{101} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$A^{102} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(6)

Complex eigenvalues / eigenvectors

$$A = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix}$$

$$\det(sI - A) = \det \begin{bmatrix} s & -2 \\ 2 & s \end{bmatrix} = s^2 + 4 = 0$$

$$s^2 = -4$$

$$s = \pm \sqrt{-4}$$

$$= \pm i2$$

$$\boxed{\tau_1 = 2i} \quad \boxed{\tau_2 = -2i}$$

$$\tau_1 = 2i$$

$$(A - \tau_1 I)x = 0$$

$$\begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix} - \begin{bmatrix} 2i & 0 \\ 0 & 2i \end{bmatrix} = \begin{bmatrix} -2i & 2 \\ -2 & -2i \end{bmatrix}$$

$$L_1(i) + L_2 \rightarrow L_2$$

$$\begin{bmatrix} -2i & 2 \\ 0 & 0 \end{bmatrix}$$

$$\Rightarrow -2ix_1 + 2x_2 = 0$$

$$\Rightarrow x_1 = -ix_2$$

$$2x_2 = 2ix_1$$

$$x = x_2 \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$E_{\tau=2i} = \text{span} \left\{ \begin{bmatrix} -i \\ 1 \end{bmatrix} \right\}$$

(7)

$$\lambda_2 = -2i$$

$$A - \lambda_2 I = \begin{bmatrix} 2i & 2 \\ -2 & 2i \end{bmatrix}$$

$$L_1 (-i) + L_2 \rightarrow L_2$$

$$\begin{bmatrix} 2i & 2 \\ 0 & 0 \end{bmatrix}$$

$$\cancel{2i}x_1 + \cancel{2}x_2 = 0$$

$$(ix_1 = -x_2) i$$

$$ix_1 = -ix_2$$

$$E_{\lambda_2} = E_{-2i} = \text{span} \left\{ \begin{bmatrix} i \\ 1 \end{bmatrix} \right\}$$

Examples of diagonalizable / non-diagonalizable matrix

Case 1

$$A = \begin{bmatrix} 1 & 5 & 3 & 1 \\ 0 & 2 & 4 & 5 \\ 0 & 0 & 3 & 2 \\ 0 & 0 & 0 & 7 \end{bmatrix}$$

eigenvalues $\lambda_1=1, \lambda_2=2, \lambda_3=3, \lambda_4=7$

4 distinct eigenvalues $\Rightarrow A$ is diagonalizable

(diagonalizable A does not imply distinct eigenvalues)

Case 2

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 3 & 4 \\ 0 & 0 & 2 \end{bmatrix} \quad \begin{bmatrix} s-2 & 0 & 0 \\ -1 & s-3 & -4 \\ 0 & 0 & s-2 \end{bmatrix}$$

$$\det(sI - A) = (s-2)^2 (s-3) = (s-2)(s-2)(s-3)$$

$\lambda_1 = 2 \leftarrow$ algebraic multiplicity
 $\lambda_2 = 2 \leftarrow$
 $\lambda_3 = 3$

For diagonalizability check geometric multiplicity for $\lambda = 2$

$$(A - \tau I)x = 0$$

$$A - 2 \cdot I = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 4 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (9)$$

$$x_1 = -x_2 - 4x_3$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 - 4x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}$$

basis for $E_{\tau=2}$ $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix} \right\}$

$\tau = 2$ has geometric multiplicity of 2
geometric multiplicity equals my
algebraic multiplicity

$\Rightarrow A$ is diagonalizable

Case 3

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 3 & 4 \\ 1 & 0 & 2 \end{bmatrix}$$

$$\tau_1 = 2$$

$$\tau_2 = 2$$

$$\tau_3 = 3$$

$$\tau = 2$$
$$A - 2I = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 4 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix}$$

(10)

$$x_1 = 0 \quad x_2 + 4x_3 = 0 \quad \leftarrow 1 \text{ free variable}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -4x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 0 \\ -4 \\ 1 \end{bmatrix}$$

geometric
multiplicity of
1

basis for
 $E_{\lambda=2}$

$\Rightarrow A$ is not diagonalizable

Singular Value Decomposition (SVD)

Factorization for non-diagonalizable matrices (square, non-square)

Factorize matrix as follows

$$A = U \Sigma V^T \quad \left(\begin{array}{l} \text{diagonalizable} \\ A = PDP^{-1} \end{array} \right)$$

U composed of the left singular vectors of A

⇒ orthonormal eigenvectors of AA^T (square matrix)

V compose of the right singular vectors of A

⇒ orthonormal eigenvectors of $A^T A$ (square matrix)

Orthonormal : ~~normal~~ ^{normalized (unit)} and orthogonal vectors

normalized equal to 1

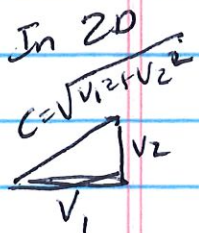
$$\|\vec{v}\| = 1$$

$$\|\vec{v}\| = \sqrt{\vec{v} \cdot \vec{v}}$$

$$= \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

$$= 1$$

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$



$$\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{aligned} a \cdot b &= a_1 b_1 + a_2 b_2 + \dots + b_n a_n \\ &= a^T b \\ &= b^T a \end{aligned}$$

12

$$a^T = [a_1 \ a_2 \ \dots \ a_n]$$

$$b^T = [b_1 \ b_2 \ \dots \ b_n]$$

Orthogonal

$$\vec{a} \perp \vec{b}$$



$$a \cdot b = 0$$

Example: