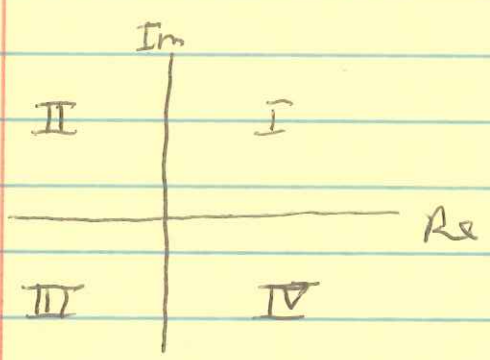


# Lecture 3 Wrap up complex numbers, Introduction to systems of linear equations

Review: Last lecture we defined the complex number of the form  $z = a + ib$ , which has the defining properties:

modulus / absolute value  $|z| = \sqrt{a^2 + b^2}$   
 $z\bar{z} = |z|^2 = a^2 + b^2$

and argument / phase  $\theta \pm 2\pi k$   $k = 0, 1, \dots$   
where  $\theta$  was determined by the quadrant



I, IV :  $\theta = \arctan\left(\frac{b}{a}\right)$   
II :  $\theta = \arctan\left(\frac{b}{a}\right) + \pi$   
III :  $\theta = \arctan\left(\frac{b}{a}\right) - \pi$

TopHat question was how many solutions are there to  $x^3 = 1$

Another way to represent 1 is  
 $1 = \cos(0 + 2\pi k) + i \sin(0 + 2\pi k)$   $k = \pm 1, \pm 2, \dots$   
 $k = 0$

$z = re^{i\theta}$   
 $r = |z|$

Recall,  $re^{i\theta} = r(\cos\theta + i\sin\theta)$

$1 = e^{i(2\pi k)}$

(2)

$$x^3 = 1 \Rightarrow x = 1^{1/3} \Rightarrow x = \left( e^{i2\pi k} \right)^{1/3} \\ = e^{i2\pi k/3}$$

$$k=0 \Rightarrow 1$$

$$k=1 \Rightarrow x = \cos\left(\frac{2\pi}{3}\right) + i\sin\left(\frac{2\pi}{3}\right)$$

$$k=2 \Rightarrow x = \cos\left(\frac{4\pi}{3}\right) + i\sin\left(\frac{4\pi}{3}\right)$$

Remark:  $m$ th roots of an arbitrary complex number  $z = re^{i\theta}$  are the  $m$  distinct  $m$ th roots of  $z$  are given by

$$z^{1/m} = \sqrt[m]{|z|} e^{i(\theta + 2\pi k)/m}$$

$$k = 0, 1, 2, \dots, m-1$$

## Systems of linear equations

Systems of linear equations play an important and motivating role in the subject of linear algebra

Basic definition:

A linear equation in unknowns  $x_1, x_2, \dots, x_n$  is an equation that can be put in the standard form

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b \quad (1)$$

where  $a_1, a_2, \dots, a_n$  and  $b$  are constants, termed coefficients

A solution of (1) is a set of values  $x_1, \dots, x_n$  that satisfy (1).

Example: Consider the linear equation

$$\frac{1}{2}x_1 + x_2 = 0$$

$$a_1 = \frac{1}{2}, a_2 = 1, b = 0$$

Rearrange terms to show

$$x_1 = -2x_2 \Rightarrow \text{infinite number of solutions}$$

choose any  $x_2$  and solve for  $x_1$

$x_2$  is a free variable



System of linear equations is a list of linear equations with the same unknowns.

A system of  $m$  linear equations  $L_1, L_2, \dots, L_m$  in  $n$  unknowns  $x_1, x_2, \dots, x_n$  can be put in the standard form

$$\begin{aligned} L_1: & a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ L_2: & a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ & \vdots \\ L_m: & a_{m1}x_1 + a_{m2}x_2 + \dots + a_{m\overset{n}{n}}x_n = b_m \end{aligned}$$

$b_i, a_{ij}$  : constants

$i$  : refers to equation  $L_i$   
 $j$  : coefficient of unknown variable  $x_j$

The system above is called an  $m \times n$  (read  $m$  by  $n$ ) system. It is called a square system if  $m=n$ , that is, the number  $m$  of equations is equal to the number  $n$  of unknowns.

Consider the following  $2 \times 2$  system

$$L_1: \frac{1}{2}x_1 + x_2 = 0$$

$$L_2: 0 \cdot x_1 + x_2 = 5$$

$$L_2: x_2 = 5$$

$$L_1: x_1 = -2x_2 = -2 \cdot 5 = -10$$

one unique solution

$$x_1 = -10, x_2 = 5$$

Example

Now consider the case

$$L_1: \frac{1}{2}x_1 + x_2 = 0$$

$$L_2: 0 \cdot x_1 + 0 \cdot x_2 = b$$

if  $b \neq 0$ , the  $L_2$  is a degenerate linear equation (inconsistent) and the  $2 \times 2$  system has no solutions.

if  $b = 0$ , the  $2 \times 2$  system has infinite solutions.

Finally, consider the case

$$L_1: \frac{1}{2}x_1 + x_2 = 0$$

$$L_2: x_1 + 2x_2 = 0$$

$$L_1 \Rightarrow x_1 = -2x_2 \quad \text{same!}$$

$$L_2 \Rightarrow x_1 = -2x_2$$

Summary: A system of linear equations has three types of solutions

- (1) Exactly one solution
- (2) No solution
- (3) Infinite solutions

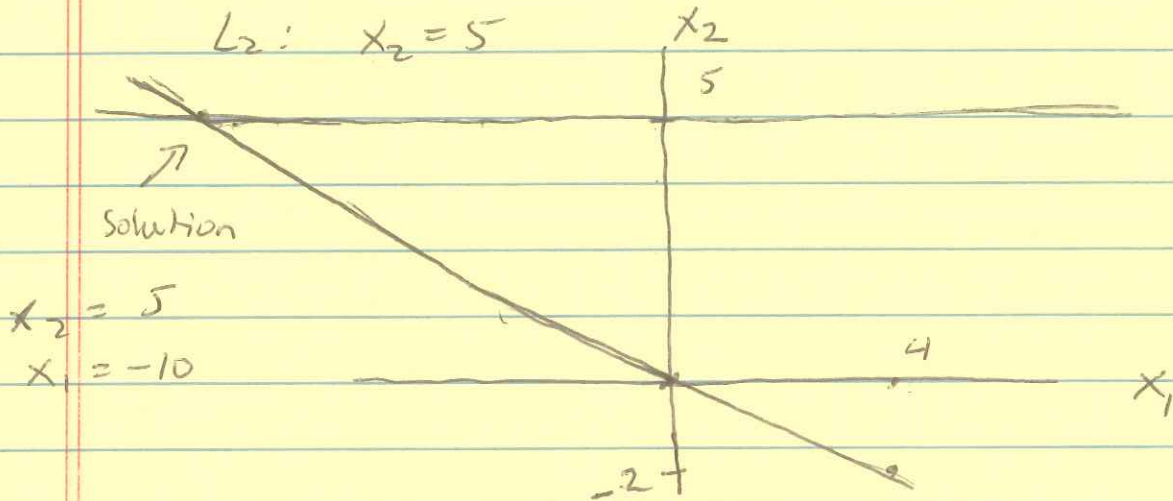
We can visualize these 3 scenarios plotting the equations

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(1) One solution

$$L_1: \frac{1}{2}x_1 + x_2 = 0 \Rightarrow x_2 = -\frac{1}{2}x_1$$

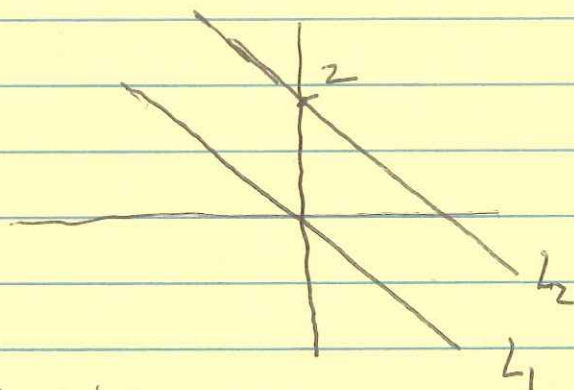
$$L_2: x_2 = 5$$



(2) No solution

$$L_1: \frac{1}{2}x_1 + x_2 = 0 \Rightarrow x_1 = -2x_2$$

$$L_2: \frac{1}{2}x_1 + x_2 = 1 \Rightarrow x_1 = -2x_2 + 2$$

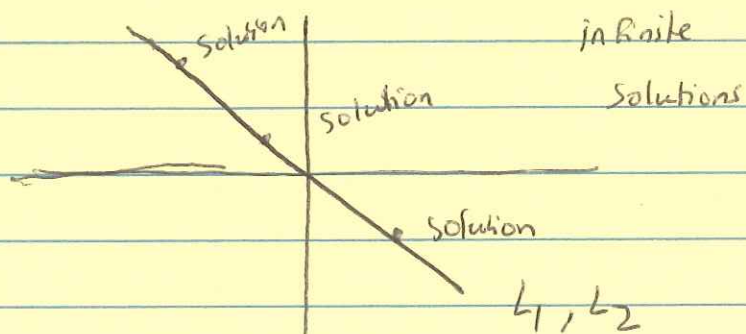


no intersect/  
no solution

(3) Infinite solutions

$$L_1: \frac{1}{2}x_1 + x_2 = 0$$

$$L_2: x_1 + 2x_2 = 0$$



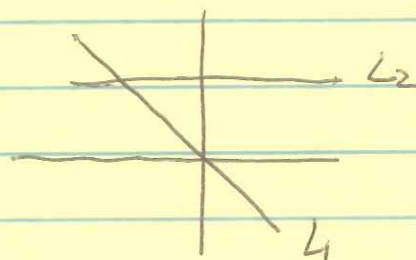


Questions:

What are the properties that resulted in these types of solutions?

What criteria must be met to ensure existence of a unique solution?

Case (1): Exactly one solution



This system is called independent

Linearly independent system

A system of  $m$  linear equations is linearly independent if no equation can be written as a linear combination of the others

Case (3): Infinite solutions

We had a linearly dependent system

$$L_1: \frac{1}{2}x_1 + x_2 = 0$$

$$L_2: x_1 + 2x_2 = 0$$

Note that  $L_2$  is just  $L_1$  multiplied by 2

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Summary : A square ( $n \times n$ ) system has a unique solution  $\text{iff}$  and only  $\text{iff}$  the system is linearly independent and consistent,