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Lecture 8

Dimension

We say a vector space V is said to be n -dimensional, written $\dim(V) = n$ if V has a basis with n ~~element~~ elements

The vector space $\{0\}$ is defined to have dimension zero

$$\dim\left(\text{span}\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}\right) = 0$$

standard basis

$$\dim(\mathbb{R}^2) = 2$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\dim(\mathbb{R}^3) = 3$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Lemma: Suppose $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ spans V , then a set of $n+1$ or more vectors in V are linearly dependent

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What is $\dim(\text{rowsp}(A))$

⇒ The number of vectors in a basis for the $\text{rowsp}(A)$

We can take the matrix A and reduce to echelon form. The the number of non-zero rows is the number of elements in the basis and the row vectors form a basis.

Rank

$\text{rank}(A)$ is the rank of matrix A and is equal to the max # of linearly independent rows of A , equivalently, the $\dim(\text{rowsp}(A))$

Theorem

$$\dim(\text{rowsp}(A)) = \dim(\text{colsp}(A)) = \text{rank}(A)$$

2nd basis example

Find a basis that is composed of the original vectors

Step I: Form a matrix M whose columns are the given vectors

$$M = [\vec{u}_1^T, \vec{u}_2^T, \vec{u}_3^T, \vec{u}_4^T] = \begin{bmatrix} 1 & 1 & 3 & 1 \\ 2 & 3 & 8 & 4 \\ 1 & 3 & 7 & 6 \\ 3 & 5 & 13 & 9 \end{bmatrix}$$

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Step 2: Row reduce to echelon form

$$M \sim \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

no pivot

row equivalent $\vec{u}_1^T, \vec{u}_2^T, \vec{u}_3^T, \vec{u}_4^T$

delete

Step 3: For each column without a pivot, delete (cast-out) the vector \vec{u}_k from the list

Step 4: Output the remaining vectors
basis: $\{\vec{u}_1, \vec{u}_2, \vec{u}_4\}$

$$\dim(\text{rowsp}(M)) = \dim(\text{span}\{\vec{u}_1, \vec{u}_2, \vec{u}_4\})$$

$$= \dim(\text{colsp}(M)) = \text{rank}(M) = 3$$

Some Examples

Consider

$$v_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ -2 \\ -4 \end{bmatrix}, v_3 = \begin{bmatrix} -2 \\ 6 \\ 14 \end{bmatrix}$$

Are the vectors linearly dependent?

Method 1:

- Construct a matrix composed of the vectors
- reduce to echelon form
- Count the # of non-zero rows

⇒ 2 non-zero rows $A = [v_1, v_2, v_3]$

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⇒ $\dim(\text{colsp}(A)) = 2$

⇒ A basis $\text{Span}\{v_1, v_2, v_3\}$
has 2 elements ($n=2$)

⇒ 3 vectors ($n+1$) is linearly dependent

Method 2:

Does there exist $k_1, k_2, k_3 \in \mathbb{R}$
s.t.

$$v_1 k_1 + v_2 k_2 + v_3 k_3 = 0 \quad ?$$

If so, set is linearly dependent

$$\underbrace{[v_1, v_2, v_3]}_A \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Augmented matrix

$$\begin{bmatrix} -1 & 0 & -2 & | & 0 \\ 0 & -2 & 6 & | & 0 \\ 1 & -4 & 14 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 2 & | & 0 \\ 0 & 1 & -3 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \quad \text{rank}(A) = 2$$

Check for consistency. If consistent then a solution exists, then the set is linearly dependent; for k_i not all zero

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Linearly independent example

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

only solution is $k_2 = k_1 = 0$
the "trivial" solution
 \Rightarrow linearly independent set

~~What is the dim~~

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Linear Mappings - Matrix Mappings

Generally two types of mappings

non-square matrices : mapping from
n-dimensional space to m-dimensional
space

$$m \begin{matrix} A \\ \left[\right] \\ n \end{matrix} \begin{matrix} \vec{x} \\ \left[\right] \\ n \end{matrix} = \begin{matrix} \vec{b} \\ \left[\right] \\ m \end{matrix}$$

$$(m \times n)(n \times 1) = (m \times 1)$$

square matrices : refer to mappings as
transformations

(e.g. reflection, rotation, dilation, translation)

In general let A be any $m \times n$ matrix,
then A determines ~~the~~ a mapping

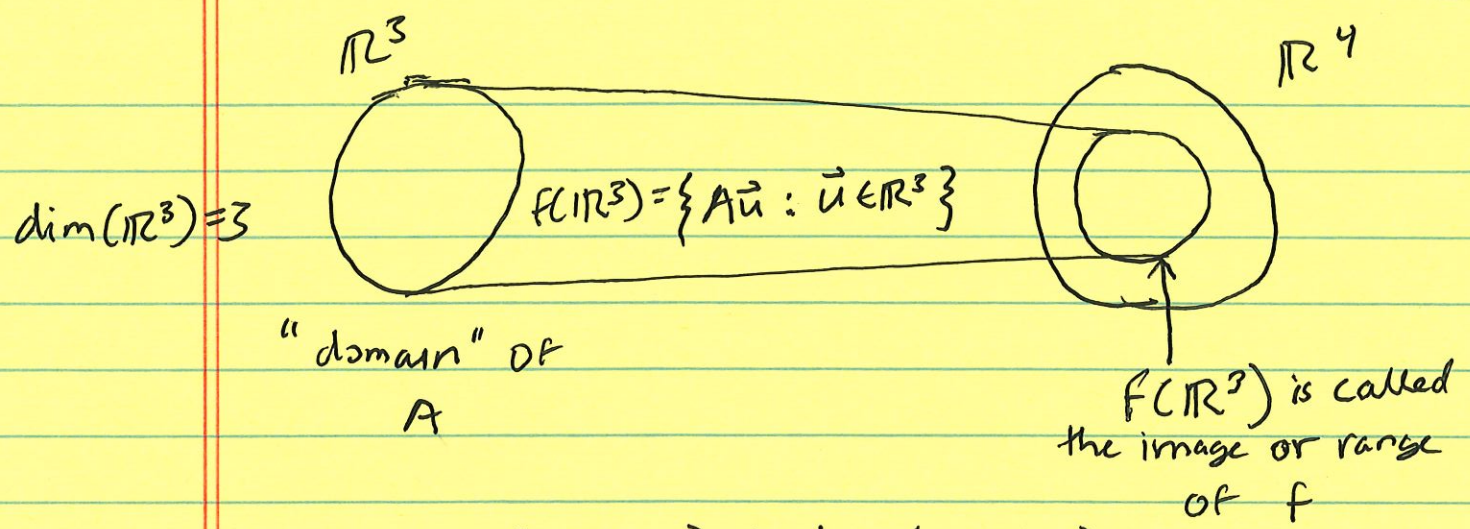
$$F_A : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

where the vectors in \mathbb{R}^m and \mathbb{R}^n
are written as columns

$$A = \begin{bmatrix} 5 & 1 & 0 \\ 4 & -1 & 1 \\ 3 & 0 & 8 \\ 0 & 1 & 2 \end{bmatrix}$$

$$F_A : \mathbb{R}^3 \rightarrow \mathbb{R}^4$$

$$F_A(\vec{u}) = A\vec{u} \in \mathbb{R}^4$$



$\dim(\text{colsp}(A)) = \dim(\text{Im}(A)) \leq 3$

image or range

$f(\mathbb{R}^3) = \text{span} \left\{ \begin{bmatrix} 5 \\ 4 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 8 \\ 2 \end{bmatrix} \right\}$

* Note that I need 4 vectors a minimum to span \mathbb{R}^4

$\dim(\text{Im}(A))$

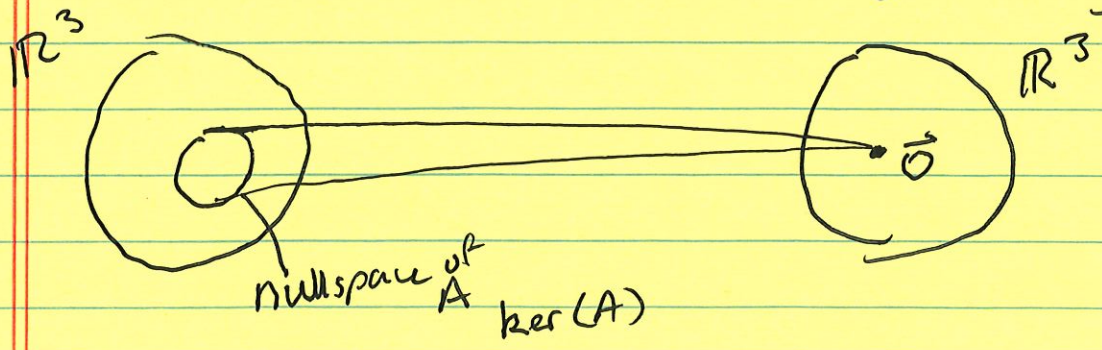
$\dim(f(\mathbb{R}^3)) = \dim(\text{Im}(A)) = 3$

Consider again vectors from H.W. p. 3

$A = \begin{bmatrix} -1 & 0 & -2 \\ 0 & -2 & 6 \\ 1 & -4 & 14 \end{bmatrix} \Rightarrow \dim(\text{colsp}(A)) = 2$

$\dim(\mathbb{R}^3) = 3$
"domain"

~~A~~ We lost a dimension along the way



A different subspace of the "domain" called the kernel of A is the set of all vectors $\vec{v} \in \mathbb{R}^n$ s.t. $A\vec{v} = \vec{0}$. These vectors are in the nullspace of A

$$\boxed{\text{nullsp}(A) = \text{ker}(A)}$$

Rank and nullity of linear mapping

$$\begin{aligned} \text{rank}(A) &= \dim(\text{Im } A) \\ \text{nullity}(A) &= \dim(\text{ker } A) \end{aligned}$$

Theorem: Let \mathbb{R}^n be of finite dimension and let $F_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$, the

$$\begin{aligned} \dim(\mathbb{R}^n) &= \dim(\text{ker } A) + \dim(\text{Im } A) \\ &= \text{nullity}(A) + \text{rank}(A) \end{aligned}$$

Ex 1 $A = \begin{bmatrix} 5 & 10 & \\ 4 & -1 & 1 \\ 3 & 0 & 8 \\ 0 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

$\text{rank}(A) = 3$

$\dim(\mathbb{R}^3) = 3 \Rightarrow \dim(\text{ker } A) = 0$

only the zero vector maps to zero!!!

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Ex 2

$$A = \begin{bmatrix} -1 & 0 & -2 \\ 0 & -2 & 6 \\ 1 & -4 & 14 \end{bmatrix}$$

$$\text{rank}(A) = 2$$

$$\dim(\mathbb{R}^3) = 3 \Rightarrow \dim(\ker A) = 1$$

How to find a basis for the nullspace
of a matrix

We are solving $A\vec{x} = \vec{b}$, where $\vec{b} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

$$\text{rref}([A \ b]) \sim \begin{bmatrix} 1 & 0 & 2 & | & 0 \\ 0 & 1 & -3 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$1 \cdot x_1 + 0 \cdot x_2 + 2 \cdot x_3 = 0$$

$$0 \cdot x_1 + 1 \cdot x_2 - 3 \cdot x_3 = 0$$

$$0 + 0 + 0 = 0$$

free variable: x_3

$$x_1 = -2x_3$$

$$x_2 = 3x_3$$

$$x_3 = 1 \cdot x_3$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} x_3 \quad \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \text{ is a solution to } A\vec{x} = \vec{0}$$

$$\text{Similarly } 5 \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \text{ solves } A\vec{x} = \vec{0}$$

nullspace $A = \text{span} \left\{ \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \right\}$

$\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix}$ is a basis for $\text{ker}(A)$

Ex 2

$$A = \begin{bmatrix} 2 & 1 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 3 & 2 & 5 & 2 \end{bmatrix}$$

$$M = [A \ \vec{0}] \sim \begin{bmatrix} 1 & 0 & 1 & 0 & | & 0 \\ 0 & 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

free variables : x_3, x_4

$$x_1 = -x_3$$

$$x_2 = -x_3 - x_4$$

$$x_3 = 1 \cdot x_3$$

$$x_4 = 1 \cdot x_4$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} x_4$$

basis for $\text{ker}(A)$ is $\left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$